

Gibbs States and Message Passing Algorithms in Random k -SAT and Graphical Models

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Outline

- 1 Introduction
- 2 Pure state/cluster decomposition
- 3 Relation with Bethe-Peierls approximation
- 4 Relation with correlation decay
- 5 Message passing algorithms
- 6 Conclusion

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Introduction

Structure of the presentation

Explore (some) interesting phenomena in **random k -SAT**

Infer general ideas (and some theorem) for a **standard model**

Ask whatever you want

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On random k -SAT:

- M. Mézard, G. Parisi, and R. Zecchina, 'Analytic and Algorithmic Solution of Random Satisfiability Problems', Science 2002
- A. Montanari, D. Shah, 'Counting good truth assignments of random k -SAT formulae', SODA 2007
- F. Krzakala, A. Montanari, F. Ricci-Tersenghi, G. Semerjian, L. Zdeborova 'Gibbs States and the Set of Solutions of Random Constraint Satisfaction Problems', PNAS 2007

Formalization:

- A. Dembo and A. Montanari, *In preparation* [DM07]

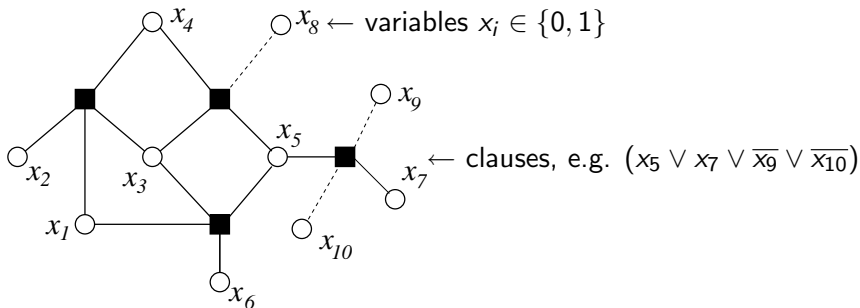
n variables: $\underline{x} = (x_1, x_2, \dots, x_n)$, $x_i \in \{0, 1\}$

m k -clauses

$$(x_1 \vee \overline{x_5} \vee x_7) \wedge (x_5 \vee x_8 \vee \overline{x_9}) \wedge \dots \wedge (\overline{x_{66}} \vee \overline{x_{21}} \vee \overline{x_{32}})$$

Hereafter $k \geq 4$ (ask me why at the end)

Uniform measure over solutions



$$F = \dots \wedge \underbrace{(x_{i_1(a)} \vee \overline{x_{i_2(a)}} \vee \dots \vee x_{i_k(a)})}_{a\text{-th clause}} \wedge \dots$$

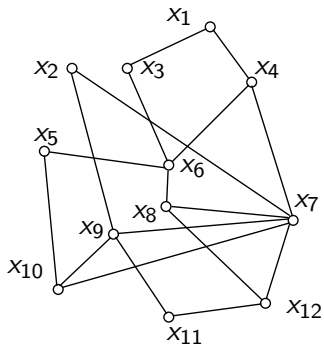
$$\mu(\underline{x}) = \frac{1}{Z} \prod_{a=1}^M \psi_a(x_{i_1(a)}, \dots, x_{i_k(a)})$$

$\mu(\underline{x}) \Leftrightarrow$ Set of solutions \mathcal{S}

Each clause is uniformly random among the $2^k \binom{n}{k}$ possible ones.

$n, m \rightarrow \infty$ with $\alpha = m/n$ fixed.

'Standard model'



$$G = (V, E), V = [n], \underline{x} = (x_1, \dots, x_n), x_i \in \mathcal{X}$$

$$\mu(\underline{x}) = \frac{1}{Z} \prod_{(ij) \in E} \psi_{ij}(x_i, x_j).$$

'Standard model' (assumptions)

1. G has bounded degree.

2. G has girth larger than 2ℓ
(with $\ell = \ell(n) \rightarrow \infty$).

3. $\psi_{\min} \leq \psi_{ij}(x_i, x_j) \leq \psi_{\max}$ uniformly.

Not *really* fulfilled by random k -SAT but ...

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Pure state/cluster decomposition

'Exponentially many clusters'

What does this mean?

[Mossel, Mézard/Palassini/Rivoire (2005),]

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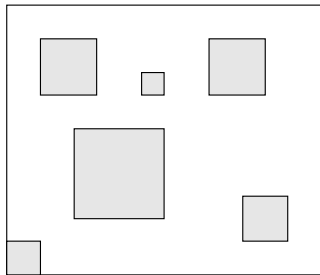
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A toy model: Random sub-cubes in $\{0, 1\}^n$

[from an idea by Dimitris Achlioptas]

$$N = 2^{n\Sigma_0} \text{ clusters: } \mathcal{S} = \cup_{a=1}^N \mathcal{S}_a$$

$\{\mathcal{S}_a\}$ iid cubes with 'centers' $\underline{x}^{(a)} \in \{0, 1, *\}^n$:

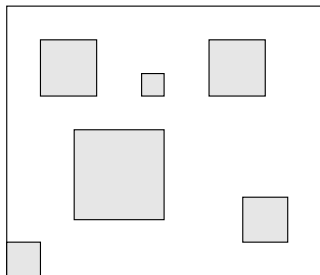


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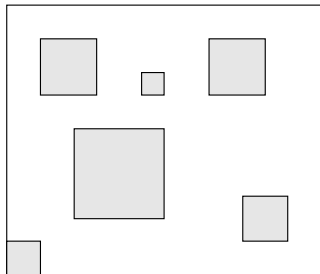


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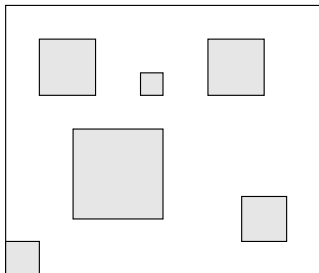
$\{\mathcal{S}_a\}$ iid cubes with 'centers' $\underline{x}^{(a)} \in \{0, 1, *\}^n$:



How shall I construct one cluster?

$$\mathcal{S}_a = \{ \underline{x} \in \{0, 1\}^n : x_i = x_i^{(a)} \}$$

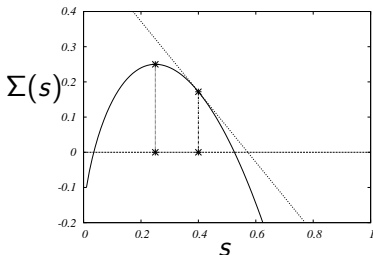
$$x_i^{(a)} = \begin{cases} * & \text{prob } p, \\ 1 & \text{prob } (1-p)/2, \\ 0 & \text{prob } (1-p)/2, \end{cases}$$



Most of clusters have size 2^{np} , but...

$$\#\{\text{clusters of size } 2^{ns}\} \doteq 2^{n\Sigma(s)}$$

$$\Sigma(s) = \Sigma_0 - D(s||p) \quad \text{if } \geq 0 \text{ and } \dots$$



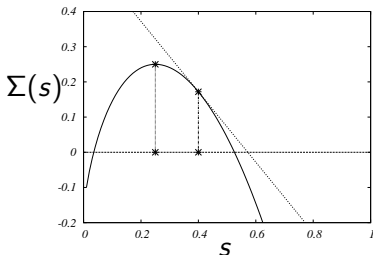
(d1RSB)

Most of solutions are in $2^{n\Sigma(s_*)}$ clusters of size 2^{ns_*} , $s_* > p$.

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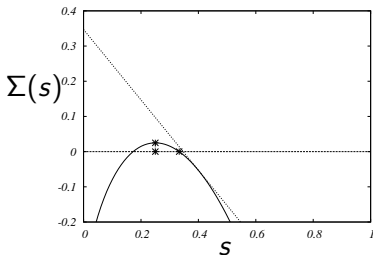
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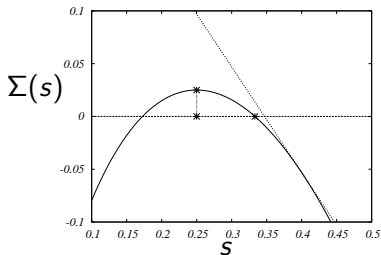
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Most of solutions are in $2^{o(n)}$ clusters of size $2^{ns_{\max}}$, $s_{\max} \in (\rho, s_*)$.

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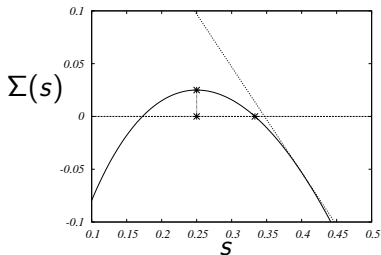
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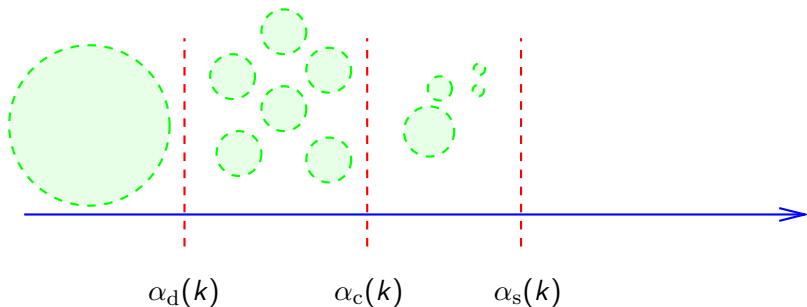


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Enough with toys...

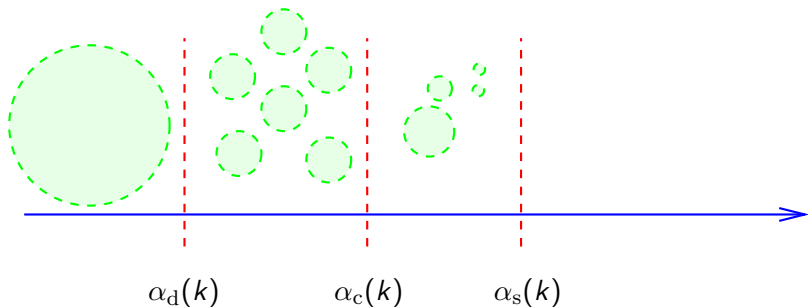
Pure states decomposition in k -SAT



[Biroli et al. 01, Mézard et al. 02, Mézard et al. 05, Achlioptas et al. 06, KMRSZ (us) 06]

The 3 scenarios seem **universal** (coloring, codes, ...)

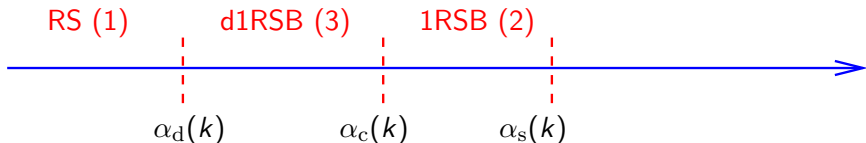
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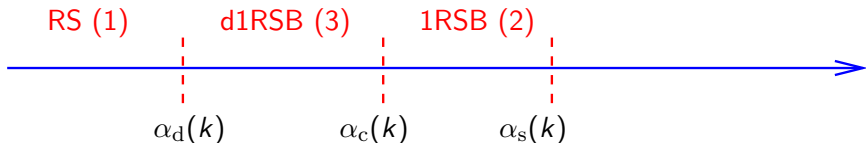
$$\alpha_d(k) = (2^k \log k)/k + \dots \quad (\alpha_d(4) \approx 9.38)$$

$$\alpha_c(k) = 2^k \log 2 - \frac{3}{2} \log 2 + \dots \quad (\alpha_c(4) \approx 9.547)$$

$$\alpha_s(k) = 2^k \log 2 - \frac{1}{2}(1 + \log 2) + \dots \quad (\alpha_s(4) \approx 9.93)$$

[Achlioptas, Naor, Peres, 2005, $\alpha_s(k) = 2^k \log 2 + O(k)$]

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How to formalize this in general?

Definition

It is the 'finer' partition $\Omega_1 \cup \dots \cup \Omega_N = \mathcal{X}^n$, such that

$$\frac{\mu(\partial_\epsilon \Omega_q)}{(1 - \mu(\Omega_q))\mu(\Omega_q)} \leq \exp\{-C(\epsilon)n\}.$$

where $C(\epsilon) > 0$ for ϵ small enough.

[the conductance of μ is exponentially small]

$$\mu(\cdot) = \sum_{q=1}^N w_q \mu_q(\cdot).$$

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Pure states: 3 scenarios

Let $N(\delta)$ the minimal number of states with measure $\geq 1 - \delta$

[RS] $N(\delta) = 1$

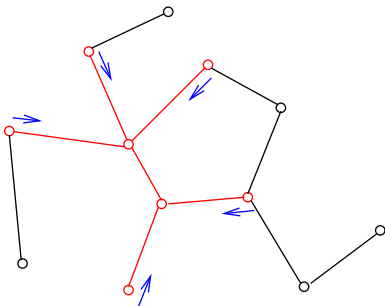
[d1RSB] $N(\delta) = e^{n(\Sigma \pm \epsilon)}$

[1RSB] $N(\delta) = \Theta(1)$ [\rightarrow unbounded random variable]

Relation with Bethe-Peierls approximation

Definition

A 'set of messages' (aka cavity fields) is a collection $\{\nu_{i \rightarrow j}(\cdot)\}$ indexed by directed edges in G , where $\nu_{i \rightarrow j}(\cdot)$ is a distribution over \mathcal{X} .



Given $F \subseteq G$, $\text{diam}(F) \leq 2\ell$, such that $\deg_F(i) = \deg_G(i)$ or ≤ 1

$$\nu_F(\underline{x}_F) \equiv \frac{1}{W(\nu_F)} \prod_{(ij) \in F} \psi_{ij}(x_i, x_j) \prod_{i \in \partial F} \nu_{i \rightarrow j(i)}(x_i).$$

Definition

A probability distribution ρ on \mathcal{X}^V is an (ε, r) Bethe state, if there exists a set of messages $\{\nu_{i \rightarrow j}(\cdot)\}$ such that, for any $F \subseteq G$ with $\text{diam}(F) \leq 2r$

$$\|\rho_F - \nu_F\|_{TV} \leq \varepsilon.$$

Consistency Condition \rightarrow Bethe Equations

Proposition (DM07)

If ρ is a $(\varepsilon, 2)$ -Bethe state with respect to the message set $\{\nu_{i \rightarrow j}(\cdot)\}$, then, for any $i \rightarrow j$

$$\|\nu_{i \rightarrow j} - \mathbb{T}\nu_{i \rightarrow j}\|_{TV} \leq C\varepsilon,$$
$$\mathbb{T}\nu_{i \rightarrow j}(x_i) = \frac{1}{z_{i \rightarrow j}} \prod_{l \in \partial i \setminus j} \sum_{x_l} \psi_{il}(x_i, x_l) \nu_{l \rightarrow i}(x_l).$$

Belief Propagation

For $t = 0, 1, \dots$

$$\nu_{i \rightarrow j}^{(t+1)} = \mathbb{T}\nu_{i \rightarrow j}^{(t)}$$

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3 Scenarios

$$\mu(\underline{x}) = \frac{1}{Z} \prod_{(ij) \in G} \psi_{ij}(x_i, x_j).$$

[consider a sequence of models with $n \rightarrow \infty$]

(RS) $\mu(\cdot)$ is a Bethe state and cannot be further decomposed.

(1RSB) $\mu(\cdot)$ is not a Bethe state but is a convex combination of Bethe states (\leftrightarrow clusters).

(d1RSB) $\mu(\cdot)$ is a Bethe state but can also be decomposed as a convex combination of Bethe states (\leftrightarrow clusters).

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Relation with correlation decay

Relation with correlation decay: Notation

- $i \in \{1, \dots, N\}$ uniformly at random.
- $B(i, r)$ ball of radius r and center i .
- $x_{\sim i, r} = \{x_j : j \notin B(i, r)\}$.

Relation with correlation decay: Definitions

Uniqueness:

$$\sup_{x, x'} \sum_{x_i} |\mu(x_i | x_{\sim i, r}) - \mu(x_i | x'_{\sim i, r})| \rightarrow 0$$

[cf. Tatikonda, Gamarnik, Bayati, ...]

Extremality:

$$\sum_{x_i, x_{\sim i, l}} |\mu(x_i, x_{\sim i, r}) - \mu(x_i)\mu(x_{\sim i, r})| \rightarrow 0$$

[cf. Peres, Mossel]

Concentration:

$$\sum_{x_{i(1)} \dots x_{i(k)}} |\mu(x_{i(1)}, \dots, x_{i(k)}) - \mu(x_{i(1)}) \dots \mu(x_{i(k)})| \rightarrow 0$$

Relation with correlation decay

RS \Leftrightarrow Extremality

d1RSB \Leftrightarrow No extremality; Concentration

1RSB \Leftrightarrow No extremality; No concentration

[First rigorous under a suitable (WEAK) interpretation of two sides]

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Theorem (Tatikonda-Jordan 02)

If μ is unique 'with rate $\delta(\cdot)$ ' then it is an (ε, r) Bethe state for any $r < \ell$ and $\varepsilon \geq C\delta(\ell - r)$, with respect to the message set output by belief propagation.

Theorem (DM07)

If μ is extremal 'with rate $\delta(\cdot)$ ' then it is an (ε, r) Bethe state for any $r < \ell$ and $\varepsilon \geq C\delta(\ell - r)$.

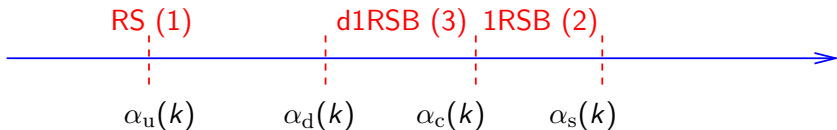
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What happens in k -SAT?



$$\alpha_u(k) = (2 \log k)/k + \dots \quad [\text{rigorous!}, \text{MS07}]$$

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Message passing algorithms

Implications

BP can work in the RS and d1RSB regimes.

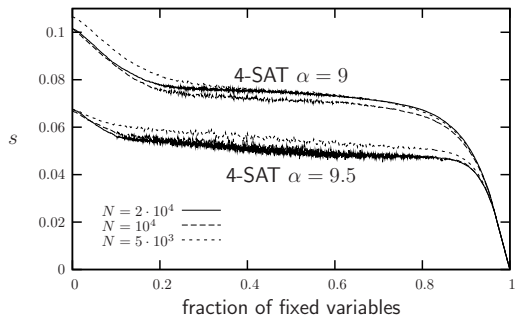
BP cannot work in the 1RSB regime.

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BP cannot work in the 1RSB regime.

Sequential BP search



Finds a solution with positive probability for $\alpha < \alpha_c(k)$.

- Many (difficult!) open problems.
- Theory of Gibbs measures (locally Markov processes) on (a class of) *finite* graphs.