

A Majorization-Minimization Approach to Design of Power Transmission Networks¹

*Mini-Workshop on Optimization and Control
Theory for Smart Grids*

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Introduction

Objective design the network, both the graph structure and the line sizes, to achieve best trade-off between efficiency (low power loss) and construction costs.

Our approach was inspired by work of Ghosh, Boyd and Saberi, *Minimizing effective resistance of a graph*, '09.

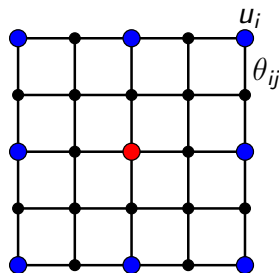
Overview

- ▶ resistive network model (DC approximation)
- ▶ convex network optimization (line sizing)
- ▶ non-convex optimization for *sparse* network design
- ▶ *robust* network design

Resistive Network Model

Basic current flow problem (power flow in AC grid):

- ▶ graph G
- ▶ injected currents b_i
 - ▶ **sources** $b_i > 0$
 - ▶ **sinks** $b_i < 0$
 - ▶ junction points $b_i = 0$
- ▶ line conductances $\theta_{ij} \geq 0$



Network conductance matrix:

$$K_{i,j}(\theta) = \begin{cases} \sum_{k \neq i} \theta_{ik}, & i = j \\ -\theta_{ij}, & \{i, j\} \in G \end{cases}$$

Solve $K(\theta)u = b$ for node potentials u_i . Line currents given by $b_{i \rightarrow j} = \theta_{ij}(u_j - u_i)$.

Resistive Power Loss

For connected G and $\theta > 0$,

$$u = \hat{K}^{-1}b \triangleq (K + 11^T)^{-1}b.$$

Power loss due to resistive heating of the lines:

$$L(\theta) = \sum_{ij} \theta_{ij} (u_i - u_j)^2 = u^T K(\theta) u = b^T \hat{K}(\theta)^{-1} b$$

For random b , we obtain the expected power loss:

$$L(\theta) = \langle b^T \hat{K}(\theta)^{-1} b \rangle = \text{tr}(\hat{K}(\theta)^{-1} \cdot \langle bb^T \rangle) \triangleq \text{tr}(\hat{K}(\theta)^{-1} B)$$

Importantly, this power loss is a *convex* function of θ .

Convex Network Optimization

We may size the lines (conductances) to minimize power loss subject to linear budget on available conductance:

$$\begin{array}{ll} \text{minimize} & L(\theta) \\ \text{subject to} & \theta \geq 0 \\ & \alpha^T \theta \leq C \end{array}$$

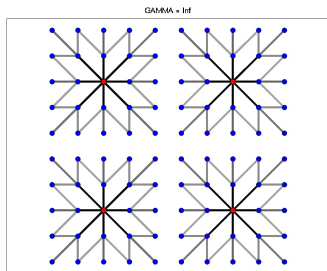
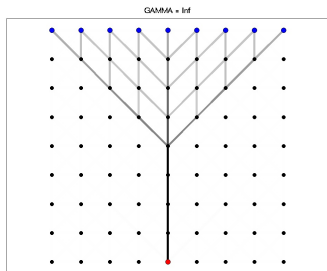
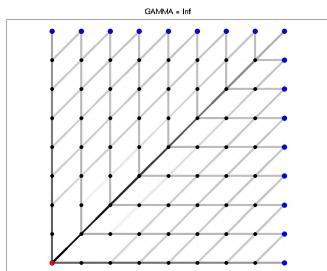
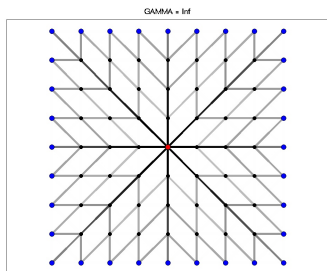
α_ℓ is cost of conductance on line ℓ .

Alternatively, one may find the most cost-effective network:

$$\min_{\theta \geq 0} \{L(\theta) + \lambda \alpha^T \theta\}$$

where λ^{-1} represents the cost of power loss (accrued over lifetime of network).

Four Examples – Optimal Network Design



Imposing Sparsity (Non-convex continuation)

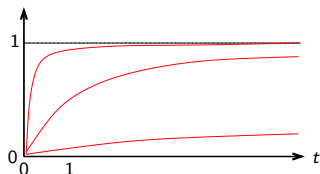
We now add a zero-conductance cost on lines:

$$\min_{\theta \geq 0} \{L(\theta) + \alpha^T \theta + \beta^T \phi(\theta)\}$$

where $\phi(t)$ is (element-wise) unit step function.

We smooth this combinatorial problem to a continuous one, replacing the discrete step ϕ by a smooth one:

$$\phi_\gamma(t) = \frac{t}{t + \gamma}$$



The convex optimization is recovered as $\gamma \rightarrow \infty$ and the combinatorial one as $\gamma \rightarrow 0$.

Majorization-Minimization Algorithm

Approach inspired by Candes and Boyd, *Enhancing sparsity by reweighted L_1 optimization*, 2009.

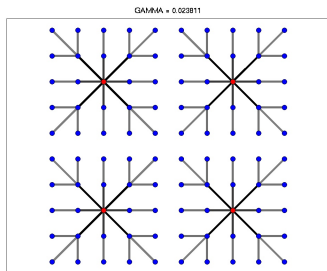
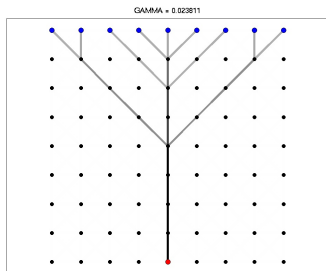
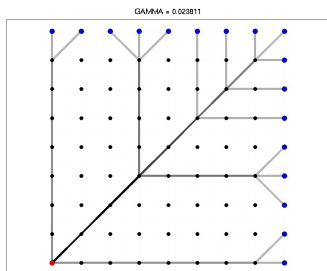
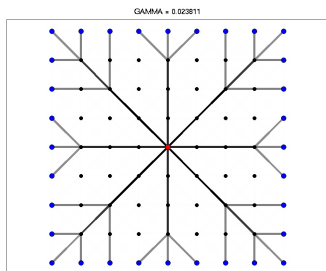
Uses *majorization-minimization* heuristic for non-convex optimization. Iteratively linearize ϕ_γ about previous solution:

$$\theta^{(t+1)} = \arg \min_{\theta \geq 0} \{L(\theta) + [\alpha + \beta \circ \nabla \phi_\gamma(\theta^{(t)})]^T \theta\}$$

results in a sequence of convex network optimization problems with reweighted α .

Monotonically decreases the objective and (almost always) converges to a local minimum.

Four Examples – Sparse Network Design



Adding Robustness

To obtain solutions that are robust of failure of k lines, we replace $L(\theta)$ by the *worst-case* power dissipation after removing k lines:

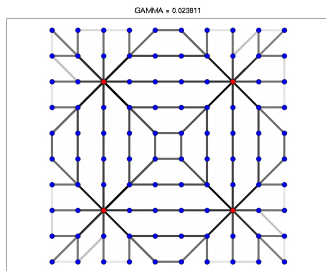
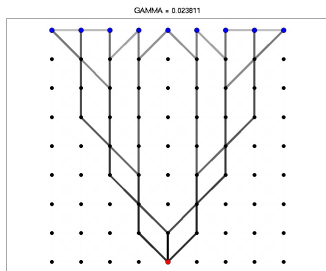
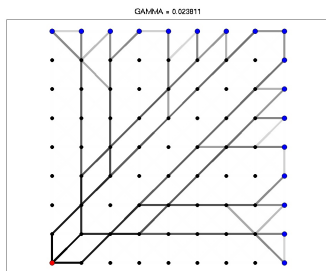
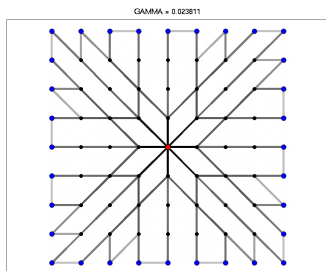
$$L^{\setminus k}(\theta) = \max_{z \in \{0,1\}^m | \mathbf{1}^T z = k} L((1 - z) \circ \theta)$$

This is still a convex function. It is tractable to compute only for small values of k .

Method can be extended to also treat failures of generators.

Solved using essentially the same methods as before...

Four Examples – Robust Network Design



Conclusion

A promising heuristic approach to design of power transmission networks. However, cannot guarantee global optimality.

Future Work:

- ▶ Bounding optimality gap?
- ▶ Use non-convex continuation approach to place generators
- ▶ possibly useful for graph partitioning problems
- ▶ adding further constraints (e.g. don't overload lines)
- ▶ better approximations to AC power flow?

Thanks!