

Synchronization and Kron Reduction in Power Networks

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Today's presentation is about a controversial topic

“Well known” observations:

- 1 power networks are coupled oscillators
- 2 Kuramoto oscillators synchronize for large coupling
- 3 graph theory quantifies coupling in a network, eg, λ_2
- 4 hence, power networks synchronize for large λ_2

... anyways, transient stability is solved

Misunderstandings between physicists and control engineers:

- 1 exact conditions for as realistic model as possible
- 2 not aiming for the most insightful and concise model

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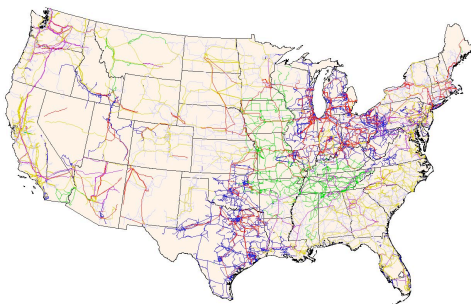
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Intro: The North American Power Grid



“... the largest and most complex machine engineered by humankind.”

[P. Kundur '94, V. Vittal '03, ...]

“... the greatest engineering achievement of the 20th century.”

[National Academy of Engineering '10]

- ① large-scale, complex, nonlinear, and rich dynamic behavior
- ② 100 years old and operating at its capacity limits

⇒ recent blackouts: New England '03 + Italy '03, Brazil '09

The New York Times

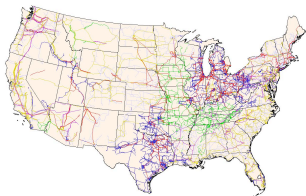
THE BLACKOUT OF 2003: Failure Reveals Creaky System, Experts Believe 8/15/2003



Energy is one of the top three national priorities

Expected additional synergetic effects in future “**smart grid**”:

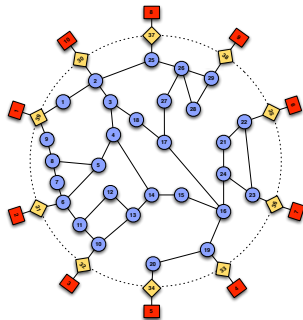
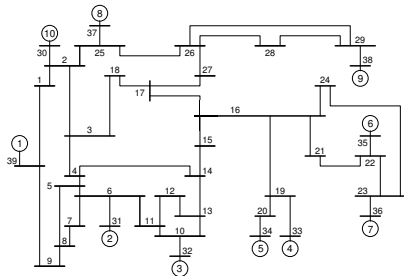
- ⇒ increasing complexity and renewable stochastic power sources
- ⇒ increasingly many transient disturbances to be detected and rejected



Transient Stability: Generators have to maintain synchronism in presence of large transient disturbances such as faults or loss of

- transmission lines and components,
- generation or load.

Intro: New England Power Grid



Power network topology:

- 1 n generators ■, each connected to a generator terminal bus ◆
- 2 n generators terminal buses ◆ and m load buses ● form connected graph
- 3 admittance matrix $\mathbf{Y}_{\text{network}} \in \mathbb{C}^{(2n+m) \times (2n+m)}$ characterizes the network

Structure-preserving DAE power network model:

- ① dynamic **swing equations** for generators ■:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + P_{\text{mech.in},i} - P_{\text{electr.out},i}$$

- active output power ■ \rightarrow ◆ :

$$P_{\text{electr.out},i} = \Re(V_i \mathbf{Y}_{\text{network},i,j}^* (V_i^* - V_j^*))$$

- $\theta_i(t)$ is measured w.r.t. a 60Hz rotating frame

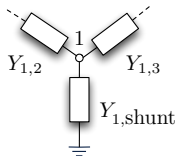
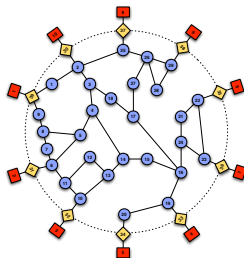
- ② passive interior network ◆ & ● :

- loads are modeled as *shunt admittances*

\Rightarrow Kirchhoff equations: $I = \mathbf{Y}_{\text{network}} V$

\Rightarrow algebraic **power flow equations** for ◆ & ● :

$$0 = V_i \sum_{j \in \blacksquare \cup \blacklozenge \cup \bullet} \mathbf{Y}_{\text{network},i,j}^* V_j^*$$



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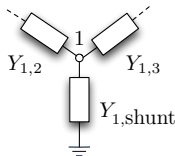
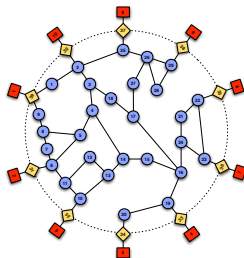
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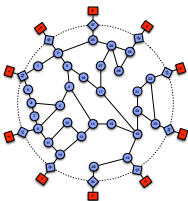
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Intro: Mathematical Model of a Power Network

Network-Reduction to an ODE power network model:

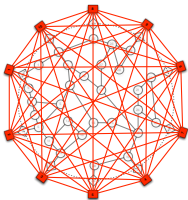


- boundary nodes (■) & interior nodes (● & ◆)
- algebraic Kirchhoff equations $I = \mathbf{Y}_{\text{network}} V$:

$$\begin{bmatrix} I_{\text{boundary}} \\ \mathbf{0} \end{bmatrix} = \begin{bmatrix} Y_{\text{boundary}} & Y_{\text{bound-int}} \\ Y_{\text{bound-int}}^T & Y_{\text{interior}} \end{bmatrix} \begin{bmatrix} V_{\text{boundary}} \\ V_{\text{interior}} \end{bmatrix}$$

Map between boundary nodes $I_{\text{boundary}} = Y_{\text{reduced}} V_{\text{boundary}}$ given by

Schur-complement: $Y_{\text{reduced}} = \mathbf{Y}_{\text{network}} / Y_{\text{interior}}$



- network reduced to active nodes (generators)
- Y_{reduced} induces complete “all-to-all” coupling graph
- active output power ■ \rightarrow ■ :

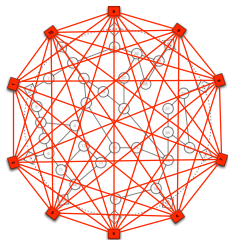
$$P_{\text{electr.out},i} = \Re(V_i \sum_{j=1}^n Y_{\text{reduced},i,j}^* V_j^*)$$

Network-Reduced ODE power network model:

classic model of interconnected **swing equations**

[Anderson et al. '77, M. Pai '89, P. Kundur '94, ...]:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$



defined on “all-to-all” reduced network Y_{reduced} with

$$P_{ij} = |V_i| |V_j| |Y_{\text{reduced},i,j}| > 0$$

is max. power transferred $i \leftrightarrow j$

$$\varphi_{ij} = \arctan(\Re(Y_{\text{reduced},i,j}) / \Im(Y_{\text{reduced},i,j})) \in [0, \pi/2)$$

reflects losses $i \leftrightarrow j$

$$\omega_i = P_{\text{mech.in},i} - |V_i|^2 \Re(Y_{\text{reduced},i,i})$$

is effective power input of i

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

Classic problem setup in transient stability analysis:

- *frequency equilibrium*: $(\dot{\theta}_i, \ddot{\theta}_i) = (0, 0)$ for all i
 - ❶ power network in stable frequency equilibrium
 - ❷ \rightarrow transient network disturbance and fault clearance
 - ❸ stability analysis of a new frequency equilibrium in post-fault network

General synchronization problem:

- *synchronous equilibrium*: $|\theta_i - \theta_j|$ bounded & $\dot{\theta}_i = \dot{\theta}_j$ for all $\{i, j\}$

synchronization in presence of transient network disturbances

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Classic analysis methods: Hamiltonian arguments

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i - \nabla_i U(\theta)^T$$

Energy function analysis or analysis of reduced gradient flow:

[N. Kakimoto et al. '78, H.-D. Chiang et al. '94]

$$\dot{\theta}_i = -\nabla_i U(\theta)^T$$

Key objective: compute domain of attraction via numerical methods

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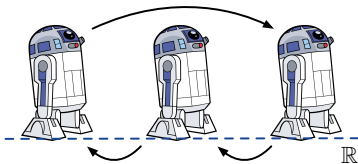
⇒ **Open problem** [D. Hill and G. Chen '06]: power system $\overset{?}{\longleftrightarrow}$ network:

transient stability, performance, and robustness of a power network
 $\overset{?}{\longleftrightarrow}$ graph properties of underlying network (topologic, spectral, etc)

Consensus protocol in \mathbb{R}^n :

$$\dot{x}_i = - \sum_{j \neq i} a_{ij} (x_i - x_j)$$

- n identical **agents** with state variable $x_i \in \mathbb{R}$
- **objective**: state agreement: $x_i(t) - x_j(t) \rightarrow 0$
- **application**: agreement and coordination algorithms, ...
- **references**: [M. DeGroot '74, J. Tsitsiklis '84, R. Olfati-Saber '04, ...]

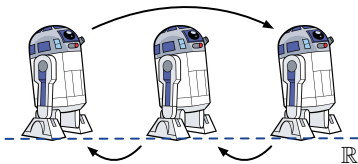


Detour – Consensus Protocols & Kuramoto Oscillators

Consensus protocol in \mathbb{R}^n :

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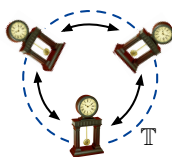
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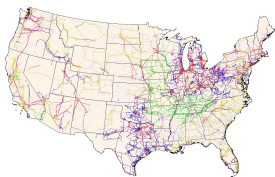


Kuramoto model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

- n non-identical **oscillators** with phase $\theta_i \in \mathbb{T}$ & frequency $\omega_i \in \mathbb{R}$
- **objective**: synchronization: $|\theta_i(t) - \theta_j(t)|$ bounded
 $\dot{\theta}_i(t) - \dot{\theta}_j(t) \rightarrow 0$
- **application**: sync phenomena
- **references**: [Y. Kuramoto '75, A. Winfree '80, S. Strogatz '00, ...]

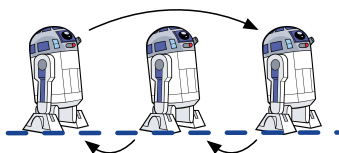




Open problem in synchronization and transient stability in **power networks**: relation to underlying network state, parameters, and topology

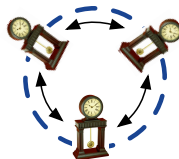
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Consensus Protocols:



$$\dot{x}_i = - \sum_{j \neq i} a_{ij} (x_i - x_j)$$

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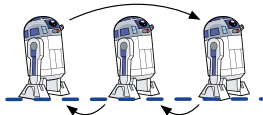
The Big Picture



Open problem in synchronization and transient stability in **power networks**: relation to underlying network state, parameters, and topology

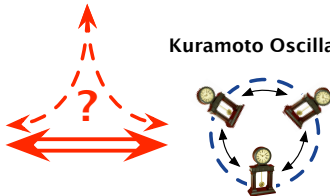
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Kuramoto Oscillators:



$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

Possible connection has often been hinted at in the literature

Power systems: [D. Subbarao et al., '01, G. Filatrella et al., '08, V. Fioriti et al., '09]

Networked control: [D. Hill et al., '06, M. Arcak, '07]

Dynamical systems: [H. Tanaka et al., '97, A. Arenas '08]

1 Introduction and Motivation

2 Singular perturbation analysis

(to relate power network and Kuramoto model)

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

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3 Synchronization analysis (of non-uniform Kuramoto model)

4 Conclusions

Time-scale separation in power network model:

$$\frac{M_i}{\pi f_0} \ddot{\theta}_i = -D_i \dot{\theta}_i + \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

- **singular perturbation parameter:** $\epsilon = \frac{M_{\max}}{\pi f_0 D_{\min}}$
- reduced dynamics on slow time-scale (for $\epsilon = 0$)
 \Rightarrow **non-uniform Kuramoto model:**

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Tikhonov's Theorem [H. Khalil '02]:

Assume the non-uniform Kuramoto model synchronizes exponentially.
Then $\forall (\theta(0), \dot{\theta}(0))$ there exists $\epsilon^* > 0$ such that $\forall \epsilon < \epsilon^*$ and $\forall t \geq 0$

$$\theta_i(t)_{\text{power network}} - \theta_i(t)_{\text{non-uniform Kuramoto model}} = \mathcal{O}(\epsilon).$$

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Singular Perturbation Analysis

Discussion of the assumption

$$\epsilon = \frac{M_{\max}}{\pi f_0 D_{\min}} \text{ sufficiently small}$$

- ① **physical interpretation:** damping and sync on separate time-scales
- ② **classic assumption** in literature on coupled oscillators: over-damped mechanical pendula and Josephson junctions
- ③ **physical reality:** with generator internal control effects $\epsilon \in \mathcal{O}(0.1)$
- ④ **simulation studies** show accurate approximation even for large ϵ
- ⑤ **topological equivalence independent of ϵ :** 1st-order and 2nd-order models have the same equilibria, the Jacobians have the same inertia, and the regions of attractions are bounded by the same separatrices
- ⑥ non-uniform Kuramoto model corresponds to reduced gradient system $\dot{\theta}_i = -\nabla_i U(\theta)^T$ **used** successfully in academia and industry since 1978

- 1 Introduction and Motivation
- 2 Singular perturbation analysis
(to relate power network and Kuramoto model)
- 3 **Synchronization analysis** (of non-uniform Kuramoto model)
- 4 Conclusions

Non-uniform Kuramoto Model in \mathbb{T}^n :

$$D_i \dot{\theta}_i = \omega_i - \sum_{j \neq i} P_{ij} \sin(\theta_i - \theta_j + \varphi_{ij})$$

- **Non-uniformity** in network: $D_i, \omega_i, P_{ij}, \varphi_{ij}$
- **Phase shift** φ_{ij} induces lossless and lossy coupling:

$$\dot{\theta}_i = \frac{\omega_i}{D_i} - \sum_{j \neq i} \frac{P_{ij}}{D_i} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$

- **Directed coupling** between oscillator i and j
- **Synchronization analysis** in multiple steps:
 - 1 phase locking: $|\theta_i(t) - \theta_j(t)|$ becomes bounded
 - 2 frequency entrainment: $\dot{\theta}_i(t) - \dot{\theta}_j(t) \rightarrow 0$
 - 3 phase synchronization: $|\theta_i(t) - \theta_j(t)| \rightarrow 0$

Main Synchronization Result

Condition on network parameters:

network connectivity $>$ network's non-uniformity + network's losses

1 Non-Uniform Kuramoto Model:

- \Rightarrow exponential synchronization: phase locking & frequency entrainment
- \Rightarrow guaranteed region of attraction: $|\theta_i(t_0) - \theta_j(t_0)| < \pi/2 - \varphi_{\max}$
- \Rightarrow gap in condition determines ultimate phase locking

2 Power Network Model:

- \Rightarrow there exists ϵ sufficiently small such that for all $t \geq 0$

$$\theta_i(t)_{\text{power network}} - \theta_i(t)_{\text{non-uniform Kuramoto model}} = \mathcal{O}(\epsilon).$$

- \Rightarrow for ϵ and network losses φ_{ij} sufficiently small, $\mathcal{O}(\epsilon)$ error converges

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Synchronization of Non-Uniform Kuramoto Oscillators

Non-uniform Kuramoto Model in \mathbb{T}^n - rewritten:

$$\dot{\theta}_i = \frac{\omega_i}{D_i} - \sum_{j \neq i} \frac{P_{ij}}{D_i} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$

Synchronization condition (\star):

$$\underbrace{n \frac{P_{\min}}{D_{\max}} \cos(\varphi_{\max})}_{\text{worst lossless coupling}} > \underbrace{\max_{\{i,j\}} \left(\frac{\omega_i}{D_i} - \frac{\omega_j}{D_j} \right)}_{\text{worst non-uniformity}} + \underbrace{\max_i \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij})}_{\text{worst lossy coupling}}.$$

\Rightarrow **phase locking**

\Rightarrow **frequency entrainment**

Proof: contraction property and time-varying consensus protocols

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Synchronization condition (★):

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⇒ phase locking

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Non-uniform Kuramoto Model in \mathbb{T}^n - rewritten:

$$\dot{\theta}_i = \frac{\omega_i}{D_i} - \sum_{j \neq i} \frac{P_{ij}}{D_i} \cos(\varphi_{ij}) \sin(\theta_i - \theta_j) + \frac{P_{ij}}{D_i} \sin(\varphi_{ij}) \cos(\theta_i - \theta_j)$$

Synchronization condition (★):

$$\underbrace{n \frac{P_{\min}}{D_{\max}} \cos(\varphi_{\max})}_{\text{worst lossless coupling}} > \underbrace{\max_{\{i,j\}} \left(\frac{\omega_i}{D_i} - \frac{\omega_j}{D_j} \right)}_{\text{worst non-uniformity}} + \underbrace{\max_i \sum_j \frac{P_{ij}}{D_i} \sin(\varphi_{ij})}_{\text{worst lossy coupling}}.$$

⇒ **phase locking**

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Proof: contraction property and time-varying consensus protocols

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Classic (uniform) Kuramoto Model in \mathbb{T}^n :

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j \neq i} \sin(\theta_i - \theta_j)$$

Synchronization condition (\star) :

$$K > \omega_{\max} - \omega_{\min}$$

Condition (\star) is **necessary and sufficient**

when considering all distributions of $\omega \in [\omega_{\min}, \omega_{\max}]$.

Condition (\star) strictly improves existing bounds on Kuramoto model:
[F. de Smet et al. '07, N. Chopra et al. '09, G. Schmidt et al. '09,
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Necessary condition synchronization: $K > \frac{n}{2(n-1)}(\omega_{\max} - \omega_{\min})$
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Condition (★★) for regular Kuramoto model:

$$K > \| [\dots, \omega_i - \omega_j, \dots] \|_2$$

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Further interesting results:

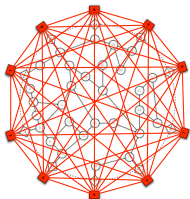
- 1 explicit synchronization frequency
- 2 exponential rate of frequency entrainment
- 3 conditions for phase synchronization
- 4 results for general non-complete graphs

... to be found in our papers.

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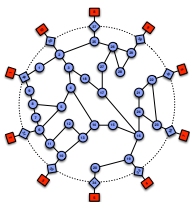
Structure-preserving power network models

So far we considered a **network-reduced** power system model:



- network reduced to generator nodes ■
- synchronization conditions on $\lambda_2(P)$ and P_{\min}
- all-to-all reduced admittance matrix $Y_{\text{reduced}} \sim P/V^2$
(for uniform voltage levels $|V_i| = V$)

Topological non-reduced **structure-preserving** power system model:



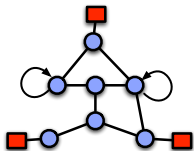
- **boundary nodes** (generators) & **interior nodes** (buses)
- topological bus admittance matrix Y_{network}
indicating transmission lines and loads (self-loops)
- **Schur-complement** relation: $Y_{\text{reduced}} = Y_{\text{network}}/Y_{\text{interior}}$
c.f. “Kron reduction”, “Dirichlet-to-Neumann map”,
“Schur contraction”, “Gaussian elimination”, ...

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Kron reduction of graphs

Kron reduction of a graph with

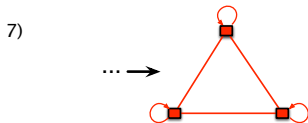
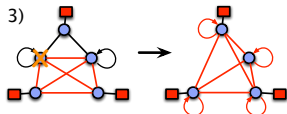
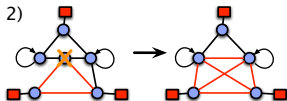
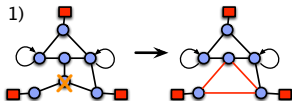
- boundary nodes ■
- interior nodes ● with nonnegative self-loops ↻
- (loopy) Laplacian matrix $\mathbf{Y}_{\text{network}}$



1 Iterative Kron reduction of a single interior node ● :

- Algebraic evolution of Laplacian matrix:
- Topological evolution of the corresponding graph

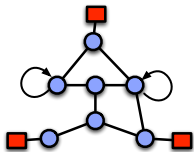
$$\mathbf{Y}_{\text{reduced}}^{k+1} = \mathbf{Y}_{\text{reduced}}^k / \bullet$$



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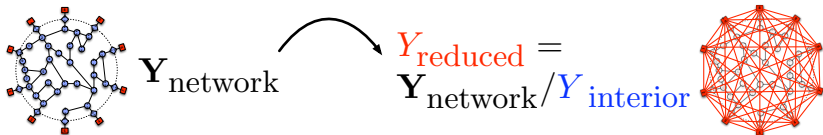
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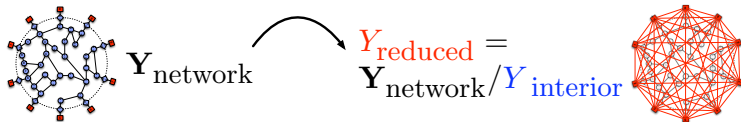
- ① Iterative Kron reduction of a single interior node ● :

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- ② Fully reduced Laplacian $\mathbf{Y}_{\text{reduced}}$ is equivalent to Schur complement:



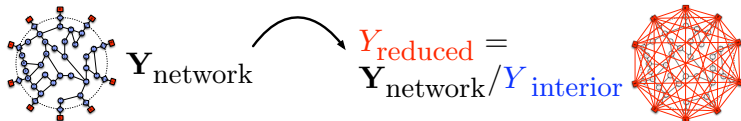
Kron reduction of graphs



Some properties of the **Kron reduction** process:

- 1 **Well-posedness:** Symmetric & irreducible (loopy) Laplacian matrices can be reduced and are closed under Kron reduction
- 2 **Topological properties:**
 - interior network connected \Rightarrow reduced network complete
 - at least one node in interior network features a self-loop \Rightarrow all nodes in reduced network feature self-loops
- 3 **Algebraic properties:** self-loops in interior network ...
 - decrease mutual coupling in reduced network
 - increase self-loops in reduced network

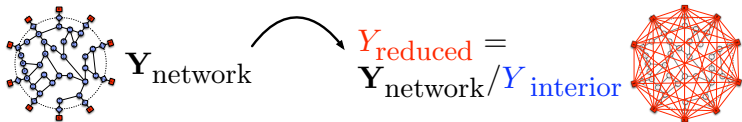
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4 Spectral properties:

- interlacing property: $\lambda_i(\mathbf{Y}_{\text{network}}) \leq \lambda_i(\mathbf{Y}_{\text{reduced}}) \leq \lambda_{i+n-|\blacksquare|}(\mathbf{Y}_{\text{network}})$

⇒ algebraic connectivity λ_2 is non-decreasing

- effect of self-loops  on loop-less Laplacian matrices:

$$\lambda_2(\mathbf{L}_{\text{reduced}}) + \max\{\textcircled{\text{blue}}\} \geq \lambda_2(\mathbf{L}_{\text{network}}) + \min\{\textcircled{\text{blue}}\}$$

$$\lambda_2(\mathbf{L}_{\text{reduced}}) + \min\{\textcircled{\text{red}}\} \leq \lambda_{2+n-|\blacksquare|}(\mathbf{L}_{\text{network}}) + \max\{\textcircled{\text{blue}}\}$$

5 Effective resistance:

- Effective resistance $R(i,j)$ among boundary nodes \blacksquare is invariant
- For boundary nodes \blacksquare : effective resistance $R(i,j)$ uniform
⇔ coupling $\mathbf{Y}_{\text{reduced}}(i,j)$ uniform ⇔ $1/R(i,j) = \frac{n}{2} |\mathbf{Y}_{\text{reduced}}(i,j)|$


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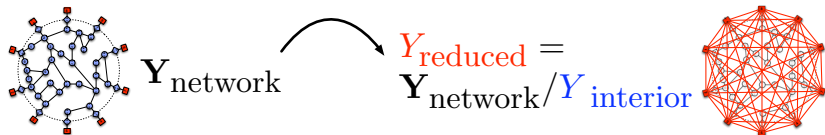
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Synchronization in structure-preserving models



Assumption I: lossless network and uniform voltage levels V at generators

① **Spectral condition for synchronization:** $\lambda_2(P) \geq \dots$ becomes

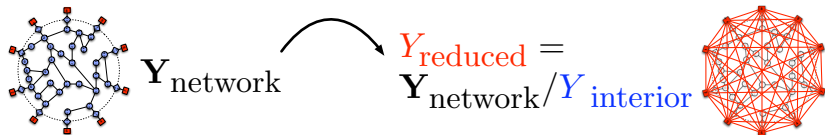
$$\lambda_2(i \cdot \mathbf{L}_{\text{network}}) > \left\| \left(\frac{\omega_2}{D_2} - \frac{\omega_1}{D_1}, \dots \right) \right\|_2 \cdot \frac{f(D_i)}{V^2} + \min\{\circlearrowleft\}$$

Assumption II: effective resistance R among generator nodes is uniform

② **Resistance-based condition for synchronization:** $nP_{\min} \geq \dots$ becomes

$$\frac{1}{R} > \max_{\{i,j\}} \left\{ \frac{\omega_i}{D_i} - \frac{\omega_j}{D_j} \right\} \cdot \frac{D_{\max}}{2V^2}$$

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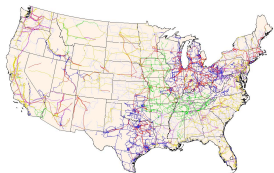
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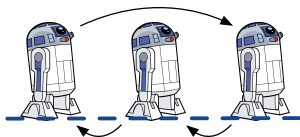
Conclusions



Open problem in synchronization and transient stability in **power networks**: relation to underlying network state, parameters, and topology

singular perturbations
and graph theory

Time-varying
Consensus Protocols



Kuramoto, consensus,
and nonlinear control tools

Non-uniform
Kuramoto Oscillators



- **Details** and **papers** can be found at: <http://motion.me.ucsb.edu>
- **Ongoing work**: more detailed models, inverters and power electronics. . .